

(11) EP 3 415 410 B1

(12)

EUROPEAN PATENT SPECIFICATION

(45) Date of publication and mention of the grant of the patent:

04.10.2023 Bulletin 2023/40

(21) Application number: 16889875.7

(22) Date of filing: 26.08.2016

(51) International Patent Classification (IPC):

B62K 5/025 (2013.01) A61G 5/10 (2006.01)

B62K 15/00 (2006.01) A61G 5/04 (2013.01)

(52) Cooperative Patent Classification (CPC): A61G 5/047; A61G 5/10; A61G 5/1059; B62K 5/025; B62K 15/00

(86) International application number: PCT/JP2016/075054

(87) International publication number: WO 2017/138174 (17.08.2017 Gazette 2017/33)

(54) SMALL ELECTRIC VEHICLE

KLEINES ELEKTROFAHRZEUG PETIT VÉHICULE ÉLECTRIQUE

(84) Designated Contracting States:

AL AT BE BG CH CY CZ DE DK EE ES FI FR GB GR HR HU IE IS IT LI LT LU LV MC MK MT NL NO PL PT RO RS SE SI SK SM TR

- (30) Priority: 10.02.2016 JP 2016023304
- (43) Date of publication of application: 19.12.2018 Bulletin 2018/51
- (73) Proprietors:
 - Toyoda Iron Works Co., Ltd. Toyota-shi Aichi 471-8507 (JP)
 - National Institute for Environmental Studies Tsukuba-shi, Ibaraki 305-8506 (JP)
 - Accurate Systems Inc. Tokyo 1010021 (JP)
- (72) Inventors:
 - KANO, Mitsutoshi Toyota-shi Aichi 471-8507 (JP)

- KONDO, Yoshinori Tsukuba-shi Ibaraki 305-8506 (JP)
- YASU, Junichi Tokyo 101-0041 (JP)
- (74) Representative: TBK
 Bavariaring 4-6
 80336 München (DE)
- (56) References cited:

EP 3 415 410 B1

Note: Within nine months of the publication of the mention of the grant of the European patent in the European Patent Bulletin, any person may give notice to the European Patent Office of opposition to that patent, in accordance with the Implementing Regulations. Notice of opposition shall not be deemed to have been filed until the opposition fee has been paid. (Art. 99(1) European Patent Convention).

30

FIELD

[0001] The present invention relates to a small-sized electric vehicle capable of assisting power of a wheelchair.

BACKGROUND

[0002] Conventionally, various techniques for assisting power of a wheelchair have been suggested. For example, a travelling assisting device for a wheelchair disclosed in JP 2006 - 000 589 A comprises a travelling device body and a mounting assisting tool, wherein the travelling device body includes a frame provided with a wheel, a pedal, a saddle, and a rotational force transmission mechanism, and the mounting assisting tool for the wheelchair is separately provided. The travelling assisting device for the wheelchair is characterized by comprising a combination of the above travelling device body and mounting assisting tool.

[0003] In order to travel with the travelling assisting device for the wheelchair, a user gets in the wheelchair, a caregiver sits down on the saddle as if he/she always gets on a bicycle and pedals with a handle of the wheelchair gripped. Then, the wheel goes round and the wheelchair is pushed to be able to travel forward. When the wheelchair stops, the wheelchair can be safely stopped by gripping a brake lever. Since the travelling device body can change an angle to left or right with respect to the wheelchair, the caregiver can change a travelling direction by turning the gripped handle to the right and left. US 5 351 774 A discloses a power drive assembly having the features in the preamble of claim 1. JP 2011 - 087 728 A, US 2012 / 0 029 697 A1, CA 2 487 630 A1, JP 2015 - 128 921 A, US 2015 / 068 828 A1, US 2007 / 051 548 A1 and JP 2012 - 056 363 A disclose further prior art.

SUMMARY

Problems to be solved by the Invention

[0004] Since an above-mentioned background technique forms a main part by combining the travelling device body including the wheel etc. with the mounting assisting tool for mounting the travelling device body on the wheelchair, it has been difficult that the travelling device body that was detached from the wheelchair and being in an independent state is made to travel.

[0005] The present invention is made in the context of circumstances mentioned above, and a problem thereof is to provide a small-sized electric vehicle that is capable of assisting power of a wheelchair coupled to the smallsized electric vehicle, and that is capable of traveling alone in a state of being detached from the wheelchair.

Means for Solving the Problems

[0006] The above-mentioned problem is solved by a small-sized electric vehicle according to claim 1.

[0007] Preferably, the receiving member is provided in the swing arm.

[0008] Preferably, the receiving member is provided in the seat.

[0009] The above-mentioned problem is further solved by a small-sized electric vehicle according to claim 4.

[0010] Preferably, the small-sized electric vehicle comprises a brake lever that is provided in the handle; and an interlocking mechanism that moves a brake lever for care provided in the push-handle of the wheelchair when the brake lever is moved.

[0011] Preferably, the small-sized electric vehicle comprises a front frame that is included an upper end to which the handle is attached; a base frame at which the front frame is pivotally supported; a main frame that is pivotally supported with respect to the base frame; and a seat that is mounted on an upper end portion of the main frame, wherein the small-sized electric vehicle is switchable between a first seated driving mode, in which driving while being seated on the seat is enable and a second seated driving mode, in which the seat and the handle are close to each other, achieved by pivoting the main frame toward the front frame in the first seated driving mode.

Effects of the Invention

[0012] The small-sized electric vehicle of claim 1 according to the invention can self-travel by the electric mechanism in an independent state in which the smallsized electric vehicle is not coupled to the wheelchair. The small-sized electric vehicle according to the invention can self-move the wheelchair, to which is coupled the small-sized electric vehicle via the coupling member, by self-traveling of the electric mechanism. Therefore, the small-sized electric vehicle according to the invention is capable of assisting power of the wheelchair coupled to the small-sized electric vehicle and is capable of traveling alone in a state of being detached from the wheelchair.

[0013] The small-sized electric vehicle according to the invention can self-move the wheelchair, to which coupled is the small-sized electric vehicle via the coupling member, by the electric mechanism. Therefore, the smallsized electric vehicle according to the invention reduces burdens on a caregiver of the wheelchair.

[0014] Further, the small-sized electric vehicle according to the invention can self-travel by the electric mechanism in the independent state in which the small-sized electric vehicle is not coupled to the wheelchair. Therefore, the small-sized electric vehicle according to the invention can be used by not only aged people but also many people regardless of age or gender and contributes to cost reduction by being used as a self-travelling vehicle unrelated to the wheelchair.

50

[0015] The small-sized electric vehicle according to the invention can be coupled to the wheelchair by the mounting member for mounting the wheelchair.

[0016] In the small-sized electric vehicle according to the invention, the rear wheels of the wheelchair are separated from the running surface when the component member of the wheelchair is mounted on the recessed part of the receiving member. Therefore, since rotation of the rear wheels of the wheelchair are unneeded at the time of moving the wheelchair by the electric mechanism, safety is ensured.

[0017] In the small-sized electric vehicle according to the invention, when the first seated driving mode is switched to the standing driving mode in which driving while standing on the board positioned nearly parallel to the running surface along with the seat is enable, the receiving member is erected between the pair of rear wheels and the recessed part is positioned on the upper side of the receiving member. Therefore, the component member of the wheelchair becomes easy to mount on the recessed part of the receiving member and the burdens on the caregiver are further reduced.

[0018] In an advantageous embodiment, providing the receiving member in the swing arm is realized that when the first seated driving mode is switched to the standing driving mode the receiving member is erected between the pair of rear wheels and the recessed part is positioned on the upper side of the receiving member.

[0019] In an advantageous embodiment, providing the receiving member in the seat is realized that when the first seated driving mode is switched to the standing driving mode, the receiving member is erected between the pair of rear wheels and the recessed part is positioned on the upper side of the receiving member.

[0020] In the small-sized electric vehicle of claim 4 according to the invention, since the push-handle for the wheelchair is fixed to the handle by the joining member, a moving operation of the wheelchair is performed by an operation of the handle performed for self-travelling by the electric mechanism.

[0021] In an advantageous embodiment, when the brake lever provided in the handle is moved, the brake lever for care provided in the push-handle of the wheel-chair is moved by a braking mechanism. Therefore, a braking operation of the brake lever for care of the wheel-chair is performed by a braking operation of the brake lever of the handle.

[0022] In the small-sized electric vehicle according to the invention, the wheelchair can be moved in the first seated driving mode, in which driving while being seated on the seat is enable or in the standing driving mode, in which driving while standing on the board positioned nearly parallel to the running surface along with the seat is enable.

[0023] In an advantageous embodiment, the wheel-chair can be moved in the first seated driving mode, in which driving while being seated on the seat is enable or in the second seated driving mode, in which the seat and

the handle are close to each other.

[0024] When the driving state of the small-sized electric vehicle according to the advantageous embodiment is switched to the second seated driving mode, the size of the small-sized electric vehicle becomes small by the seat and the handle becoming close to each other. Therefore, it becomes easy to move the wheelchair in a narrow space such as the interior of a room.

[0025] Further, in the small-sized electric vehicle according to the advantageous embodiment, when the driving state of the small-sized electric vehicle is switched to the second seated driving mode, the seat and the handle are close to each other. Therefore, a passenger of the wheelchair is positioned closer to the caregiver, communication becomes easier between them, and their affinity is improved.

BRIEF DESCRIPTION OF DRAWINGS

20 [0026]

25

30

35

40

45

50

55

[FIG.1]FIG. 1 is a side view of a folding vehicle according to the embodiment of the present invention set in a seated driving mode.

[FIG.2]FIG. 2 is a front perspective view of the folding vehicle set in the seated driving mode.

[FIG.3]FIG. 3 is a side view of the folding vehicle set in a folded mode.

[FIG.4]FIG. 4 is a front perspective view of the folding vehicle set in the folded mode.

[FIG.5]FIG. 5 is a side view of the folding vehicle set in a standing driving mode.

[FIG.6]FIG. 6 is a front perspective view of the folding vehicle set in the standing driving mode.

[FIG.7]FIGs. 7 are diagrams schematically illustrating a first lock mechanism provided between a base frame and a main frame mechanism.

[FIG.8]FIG. 8 is a diagram schematically illustrating a second lock mechanism provided between the main frame mechanism and swing arms.

[FIG.9]FIGs. 9 are diagrams schematically illustrating a third lock mechanism provided between the main frame mechanism and a seat.

[FIG. 10]FIG. 10 is a diagram schematically illustrating an operation transitioning from the folded mode to the seated driving mode or from the seated driving mode to the folded mode of the folding vehicle.

[FIG.11]FIG. 11 is a diagram schematically illustrating a locked state of the first lock mechanism and the third lock mechanism in the standing driving mode of the folding vehicle.

[FIG.12]FIG. 12 is a side view of the folding vehicle provided with the first coupling member and set in the seated driving mode.

[FIG. 13]FIG. 13 is a front perspective view of the folding vehicle provided with the first coupling member and set in the standing driving mode.

[FIG. 14]FIG. 14 is a side view of the folding vehicle

set in the standing driving mode and coupled to a wheelchair by the first coupling member.

[FIG. 15]FIGs. 15 are diagrams schematically illustrating from a back side of the wheelchair a coupling position of the wheelchair coupled to the folding vehicle set in the standing driving mode by the first coupling member or the second coupling member. [FIG. 16]FIG. 16 is a side view of the folding vehicle provided with the second coupling member and set in the seated driving mode.

[FIG. 17]FIG. 17 is a front perspective view of the folding vehicle provided with the second coupling member and set in the standing driving mode.

[FIG. 18]FIG. 18 is a side view of the folding vehicle set in the standing driving mode and coupled to the wheelchair by the second coupling member.

[FIG.19]FIG. 19 is a side view of the folding vehicle provided with the third coupling member and set in the seated driving mode.

[FIG20]FIG. 20 is a front perspective view of the folding vehicle provided with the third coupling member and set in the seated driving mode.

[FIG21]FIG. 21 is a side view of the folding vehicle set in the seated driving mode and coupled to the wheelchair by the third coupling member.

[FIG22]FIG. 22 is a side view of the folding vehicle set in the folded mode and coupled to the wheelchair by the third coupling member.

[FIG.23]FIG. 23 is a side view of the folding vehicle set in the standing driving mode and coupled to the wheelchair by the third coupling member.

DESCRIPTION OF EMBODIMENTS

[0027] A folding vehicle according to the present invention is described with reference to the drawings.

[1. Folding vehicle]

[0028] Firstly, a basic configuration of the folding vehicle according to the present embodiment is described with reference to FIG. 1 to FIG. 6.

[0029] The folding vehicle 1 includes a base frame 2 having the following form. Specifically, as illustrated in FIG. 2, FIG. 4, and FIG. 6, the base frame 2 includes a pair of side plates 2A and 2A, having a curved shape in side view, integrally coupled with each other via a flat plate 2B.

[0030] A front frame 3 is attached to a front portion of the base frame 2 pivotally in a substantially horizontal direction. A handle 4 is fixed to an upper end of the front frame 3. A cover 6 is attached to a front side of the front frame 3 via attachment members 5 and 5.

[0031] A wheel supporting frame 7 is fixed to a lower end of the front frame 3. A front wheel 8 is rotatably supported by the supporting frame 7. The front wheel 8 incorporates an in-wheel motor M that is driven by a battery 14 described later. Namely, the folding vehicle 1 self-

travels with the in-wheel motor M and the battery 14 etc. The in-wheel motor M is well-known and thus will not be described in detail herein.

[0032] A main frame mechanism 9 is pivotally supported by both rear side portions of the base frame 2. The main frame mechanism 9 includes: first frame members 10 pivotally supported by outer surface upper portions of the side plates 2A, via a pivotally supporting member 2C; and second frame members 11 pivotally supported by outer surface lower portions of the side plates 2A, via a pivotally supporting member 2D, while being in parallel with the first frame members 10, at a position separated from the first frame members 10 by a predetermined distance. The first frame member 10 and the corresponding second frame member 11 are coupled to each other via a link member 12 in parallel with a line A passing through a pivot center of the first frame member 10 at the pivotally supporting member 2C and a pivot center of the second frame member 11 at the pivotally supporting member 2D. Thus, the first frame member 10 and the second frame member 11 form a parallel link mechanism.

[0033] A board 13 is disposed between the two first frame members 10 in parallel with each other (see FIG. 2). The battery 14, connected to the in-wheel motor M that drivingly rotates the front wheel 8, is disposed on a lower surface side of the board 13. A footrest 15 is attached to each of the side plates 2A of the base frame 2. [0034] A first lock mechanism L1, described later, is provided between the first frame member 10 of the main frame mechanism 9 and the base frame 2.

[0035] A seat (seat part) 16 (hereinafter, referred to as "seat 16") is attached to upper end portions of the first frame members 10 and the second frame members 11 in the main frame mechanism 9. More specifically, the seat 16 is pivotally attached to the upper end portions of the two first frame members 10 via pivotally supporting members 10A in a front portion of a supporting plate 17 provided on a lower surface of the seat 16. A third lock mechanism L3 is provided between a rear portion of the supporting plate 17 and the upper end portions of the second frame members 11. The seat 16 can pivot in a counterclockwise direction from a state illustrated in FIG. 1 and FIG. 3, based on locking and unlocking functions of the third lock mechanism L3, described later.

45 [0036] A pair of swing arms 18 each have one end pivotally supported by a substantially center portion of a corresponding one of the second frame members 11 in a longitudinal direction via pivotally supporting members 11A. The swing arms 18 each have the other end pivotally supporting a shaft 19 (see FIG. 2). A pair of rear wheels 20 and 20 (see FIG. 6) are rotatably supported on both ends of the shaft 19.

[0037] A second lock mechanism L2, described later, is provided between the second frame members 11 and the swing arms 18.

[0038] Next, the first lock mechanism L1 provided between the first frame members 10 of the main frame mechanism 9 and the base frame 2 is described with

15

25

35

40

45

50

55

reference to FIG. 7.

[0039] In FIGs. 7(a) and 7(b), a striker 21, as a link member, is pivotally supported at the first frame member 10 of the main frame mechanism 9 via a supporting portion 21A. The striker 21 is a rod-shaped member having a substantially U shape in plain view. In FIG. 7(a), the striker 21 has a lower portion serving as an engaged portion 21 B engaged with a hook portion 23A of a hook member 23 described later.

[0040] A receiving member 22 is fixed to the flat plate 2B in a bottom portion of the base frame 2. A U-shaped groove 22 A having a U shape in side view is formed on the receiving member 22. The hook member 23 including the hook portion 23A is pivotally supported at the receiving member 22 via a supporting member 23B. The hook member 23 is constantly urged in the counterclockwise direction by a spring incorporated therein.

[0041] A release lever 24 has one end coupled with the hook member 23. When the other end of the release lever 24 is pulled in a right direction in FIGs. 7(a) and 7(b), against urging force of the spring in an appropriate way, the hook portion 23A of the hook member 23 engaged with the engaged portion 21B of the striker 21 is pivoted in a clockwise direction. Thus, the engagement between the engaged portion 21 B of the striker 21 and the hook portion 23A of the hook member 23 is released. [0042] The main frame mechanism 9 is locked with the base frame 2, with the first lock mechanism L1 having the configuration described above, in the following manner. Specifically, as illustrated in FIG. 7(a), the engaged portion 21B of the striker 21 is set up in the U-shaped groove 22A of the receiving member 22, and the hook member 23 is pivoted in the counterclockwise direction by the urging force of the spring. Thus, the base frame 2 and the main frame mechanism 9 are locked as in a state illustrated in FIG. 7(a).

[0043] The locking between the base frame 2 and the main frame mechanism 9 can be released by pulling the release lever 24 in the right direction in FIG. 7(b) and releasing the engagement between the engaged portion 21B of the striker 21 and the hook portion 23A of the hook member 23.

[0044] Next, the second lock mechanism L2 provided between the second frame member 11 of the main frame mechanism 9 and the swing arm 18 is described with reference to FIG. 8.

[0045] In FIG. 8, a rod member 25 has one end pivotally supported at a position of the second frame member 11 above the pivotally supporting member 11 A pivotally supporting the swing arm 18, via the pivotally supporting member 11B. A stopper engaging portion 25A having a rod shape is formed at the other end of the rod member 25

[0046] A stopper part 18A is formed on the swing arm 18 pivotally supported by the second frame member 11 via the pivotally supporting member 11A. The stopper engaging portion 25A of the rod member is engaged with the stopper part 18A from the above.

[0047] The second frame member 11 and the swing arm 18 can be locked, with the second lock mechanism L2 having the configuration described above, in the following manner. Specifically, the second frame member 11 and the swing arm 18 are pivoted with respect to each other, and the stopper engaging portion 25A of the rod member 25 is engaged with the stopper part 18A of the swing arm 18. The engaging can be released by pivoting the second frame member 11 and the swing arm 18 with respect to each other, and detaching the stopper engaging portion 25A of the rod member 25 from the stopper part 18A of the swing arm 18.

[0048] Next, the third lock mechanism L3 provided between the rear portion of the supporting plate 17 of the seat 16 and the upper end portion of the second frame member 11 is described with reference to FIG. 9. In FIG. 9, the supporting plate 17 is omitted to facilitate the understanding.

[0049] The striker 26 is a linear rod-shaped member bridging between supporting members 50 attached to the upper end portions of the two second frame members 11, and serves as an engaged portion 26A engaging with a hook portion 28A of a hook member 28 described later as illustrated in FIG. 9(a).

[0050] The receiving member 27, on which a U-shaped groove 27 A having a U shape in side view is formed, is fixed on a bottom portion of the seat 16. The hook member 28 including the hook portion 28 A is pivotally supported at the receiving member 27 via a supporting member 28B. The hook member 28 is constantly urged in the clockwise direction by a spring incorporated therein.

[0051] A release lever 29 has one end coupled with the hook member 28. When the other end of the release lever 29 is pulled in the right direction in FIGs. 9(a) and 9(b), against urging force of the spring in an appropriate way, the hook portion 28A of the hook member 28 engaged with the engaged portion 26A of the striker 26 is pivoted in the counterclockwise direction. Thus, the engagement between the engaged portion 26A of the striker 26 and the hook portion 28A of the hook member 28 is released.

[0052] The seat 16 and the upper end of the second frame member 11 are locked, with the third lock mechanism L3 having the configuration described above, in the following manner. Specifically, as illustrated in FIG. 9(a), the engaged portion 26A of the striker 26 is set up in the U-shaped groove 27A of the receiving member 27, and the hook member 28 is pivoted in the clockwise direction by the urging force of the spring. Thus, the seat 16 and the second frame member 11 are locked as in a state illustrated in FIG. 9(a).

[0053] The locking of the seat 16 and the second frame member 11 can be released by pulling the release lever 29 in the right direction in FIGs. 9(a) and 9(b) and releasing the engagement between the engaged portion 26A of the striker 26 and the hook portion 28A of the hook member 28.

[0054] As illustrated in FIG. 10, a striker 30, having a

30

40

45

50

configuration similar to that of the striker 21, is pivotally supported at a rear end portion of the swing arm 18 (around a right end portion in FIG. 10) via a pivotally supporting portion 31. The striker 30 is a rod-shaped member having a substantially U shape in plain view, and has an engaged portion 32 engaged with the hook portion 23A of the hook member 23 in the first lock mechanism L1, on the side opposite to the pivotally supporting portion 31, as described below.

[0055] Next, a relationship between the lock mechanisms described above and folding vehicle 1 in a folded mode, a seated driving mode, and a standing driving mode is described.

[0056] To begin with, the folding vehicle 1 is assumed to be in the seated driving mode as illustrated in FIGs. 1 and 2.

[0057] When the folding vehicle 1 is in the seated driving mode, the first lock mechanism L1 and the second lock mechanism L2 are each in the locked state.

[0058] More specifically, as illustrated in FIG. 7(a), the engaged portion 21B of the striker 21 in the first lock mechanism L1 is fit in the U-shaped groove 22A of the receiving member 22, and the hook portion 23A of the hook member 23 is engaged with the engaged portion 21 B of the striker 21.

[0059] As illustrated in FIG. 8, the stopper engaging portion 25A of the rod member 25 of the second lock mechanism L2 is engaged with the stopper part 18A of the swing arm 18.

[0060] As a result, the seated driving mode is maintained with the first lock mechanism L1 and the second lock mechanism L2 cooperating to lock the base frame 2 and the main frame mechanism 9 to achieve the state illustrated in FIG. 1, FIG. 2, FIG. 7(a), and FIG. 8. Thus, a driver can enjoy safe seated driving while being seated on the seat 16 (self-travelling of the folding vehicle 1).

[0061] The seated driving mode transitions to the folded mode illustrated in FIGs. 3 and 4 in the following manner. First of all, the release lever 24 is pulled in the right direction in FIG. 7(b) to release the locking of the base frame 2 and the main frame mechanism 9. Thus, the engagement between the engaged portion 21B of the striker 21 and the hook portion 23A of the hook member 23 is released, whereby the locking by the first lock mechanism L1 is released. The second frame member 11 and the swing arm 18 are pivoted with respect to each other, and thus the stopper engaging portion 25A of the rod member 25 is detached from the stopper part 18A of the swing arm 18, whereby the locking by the second lock mechanism L2 is released.

[0062] Then, the main frame mechanism 9, which has become pivotable with respect to the base frame 2 as a result of the above process, is pivoted toward the front frame 3. In this process, the second lock mechanism L2 is unlocked, and thus the swing arm 18 approaches the front frame 3 as the main frame mechanism 9 pivots. Thus, the main frame mechanism 9 and the swing arm 18 are in the folded mode in illustrated in FIGs. 3 and 4.

[0063] In the folded mode the engaged portion 32 of the striker 30 pivotally supported at the swing arm 18 is fit in the U-shaped groove 22A of the receiving member 22 in the first lock mechanism L1, and the hook portion 23A of the hook member 23 is engaged.

[0064] Thus, in the folded mode, the main frame mechanism 9 can be prevented from pivoting from the front frame 3, whereby the folded mode can be stably maintained.

[0065] Even in the folded mode, a driver can enjoy the safe seated driving while being seated on the seat 16 (self-travelling of the folding vehicle 1).

[0066] When the seated driving mode illustrated in FIGs. 1 and 2 transitions to the standing driving mode illustrated in FIGs. 5 and 6, the following operation is performed. Specifically, as in the case described above, the release lever 24 is pulled in the right direction in FIG. 7(b) to release the locking between the base frame 2 and the main frame mechanism 9, and the engagement between the engaged portion 21 B of the striker 21 and the hook portion 23A of the hook member 23 is released, whereby the first lock mechanism L1 is unlocked. The second frame member 11 and the swing arm 18 are pivoted with respect to each other to detach the stopper engaging portion 25A of the rod member 25 from the stopper part 18A of the swing arm 18, whereby the second lock mechanism L2 is unlocked. Furthermore, the release lever 29 is pulled in the right direction in FIG. 9(a) and 9(b) to release the engagement between the engaged portion 26A of the striker 26 and the hook portion 28A of the hook member 28, whereby the third lock mechanism L3 is further unlocked.

[0067] The main frame mechanism 9, which has become pivotable with respect to the base frame 2 as a result of the above process, is pivoted in a direction of moving away from the front frame 3 (namely, the swing arm 18 side) as illustrated in FIG. 10. In this process, the second lock mechanism L2 is unlocked, and thus the swing arm 18 moves away from the front frame 3 as the main frame mechanism 9 pivots. Thus, the main frame mechanism 9 and the swing arm 18 are in the standing driving mode as illustrated in FIG. 11. In the standing driving mode, as illustrated in FIG. 5, the board 13 and the seat 16 are positioned substantially parallel to a running surface G.

[0068] In the standing driving mode, the engaged portion 21B of the striker 21 in the first lock mechanism L1 is fit in the U-shaped groove 22A of the receiving member 22, and the hook portion 23A of the hook member 23 is engaged with the engaged portion 21B of the striker 21. The engaged portion 32 of the striker 30 pivotally supported at the swing arm 18 is set up in the U-shaped groove 27A of the receiving member 27 in the third lock mechanism L3, and the hook member 28 is pivoted in the counterclockwise direction by the urging force of the spring, whereby the third lock mechanism L3 is locked. [0069] Thus, in the standing driving mode, the base frame 2 and the main frame mechanism 9 as well as the

20

40

45

50

main frame mechanism 9 and the swing arm 18 can be locked with each other in a state illustrated in FIG. 11. Thus, the driver on the board 13 can enjoy the safe standing driving (self-traveling of the folding vehicle 1).

[0070] The brake levers provided to both sides of the handle 4, wiring between the brake levers and brakes, electric wiring for a power supply for driving the in-wheel motor M, and the like which are omitted in the present embodiment may be appropriately set in the actual implementation.

[0071] In the present embodiment, the third lock mechanism L3 needs to be unlocked when the folding vehicle 1 is set in the standing driving mode. As described above, the standing driving mode may be achieved with the state of locking the seat 16 to the first frame member 10 and the second frame member 11 maintained and without unlocking the third lock mechanism L3, by appropriately setting the attaching positions of the first frame member 10 and the second frame member 11, forming the parallel link mechanism, on the base frame 2, and the mounting condition of the seat 16 to the first frame member 10 and the second frame member 11.

[2. Coupling member]

[0072] Next, a coupling member for coupling the wheelchair to the folding vehicle 1 is described. In the present embodiment, the first coupling member, the second coupling member, or the third coupling member is provided in the folding vehicle 1 as the coupling member. Hereinafter, the first coupling member, the second coupling member, and the third coupling member are described sequentially.

[2.-1 first coupling member]

[0073] Firstly, the first coupling member is described with reference to FIGs. 12 to 15. The first coupling members 61 are flat plates formed into a substantially trapezoidal shape in side view of FIG. 12 and is provided at the same locations of each swing arm 18. A recessed part 63 pierced into a semicircular shape in side view of FIG. 12 is provided in an upper bottom 62 of the first coupling member 61. A lower bottom 64 of the first coupling member 61 is fixed to an outer side surface of the swing arm 18 directly facing the rear wheel 20.

[0074] As illustrated in FIG. 13, when the folding vehicle 1 is set in the standing driving mode, a pair of first coupling members 61, 61 moves to between a pair of rear wheels 20, 20. Between the pair of rear wheels 20, 20, the pair of first coupling members 61, 61 is in a state each standing along a side surface of the seat 16, and faces to each other via the seat 16. Further, each of the recessed parts 63, 63 is positioned on an upper side of each of the first coupling members 61, 61 between the pair of rear wheels 20, 20, and faces to each other via the seat 16

[0075] As illustrated in FIG. 14, in the folding vehicle 1

in the standing driving mode, when component members of the wheelchair 101 (for example, a cross pipe or a coupling pipe described later) are mounted on the recessed part 63 of the first coupling member 61, the wheelchair 101 is mounted in a state separating rear wheels 102 from the running surface G. As a result, the wheelchair 101 can be moved by the folding vehicle 1 in the standing driving mode. A reference sign 103 indicates a push-handle of the wheelchair 101.

[0076] When the wheelchair 101 has a foldable structure, as illustrated in FIG. 15(a), the cross pipe 104 is mounted on the recessed part 63 of the first coupling member 61 at a position nearer to the rear wheels 102 from a center in a longitudinal direction of the cross pipe 104 (positions indicated by arrows X). Meanwhile, when the wheelchair 101 has a structure which is not able to be folded, as illustrated in FIG. 15(b), the coupling pipe 105 is mounted on the recessed part 63 of the first coupling member 61 at a position nearer to the rear wheels 102 from a center in a longitudinal direction of the coupling pipe 105 (positions indicated by arrows Y).

[2.-2 Second coupling member]

[0077] Next, the second coupling member is described with reference to FIGs. 16 to 18. Second coupling members 71 are pipes made of a metal and formed into a substantially M-shape in side view of FIG. 16 and are each provided at the same positions on both side surfac-30 es of the seat 16 on the each rear wheel 20, 20 side. A front portion of the second coupling member 71 is fixed to the side surface of the seat 16 at a position nearer to the front frame 3 from a center in a longitudinal direction of the seat 16. Meanwhile, a rear portion of the second coupling member 71 is fixed to a rear end of the side surface of the seat 16. A recessed part 72 formed into a substantially inverse V-shape in side view of FIG. 16 is provided on an upper side of the second coupling member 71.

[0078] As illustrated in FIG. 17, when the folding vehicle 1 is set in the standing driving mode, a pair of the second coupling members 71, 71 moves to between the pair of rear wheels 20, 20. Between the pair of rear wheels 20, 20, the pair of second coupling members 71, 71 is in a state each standing along the side surface of the seat 16 and faces to each other via the seat 16. Further, between the pair of rear wheels 20, 20, each of the recessed parts 72, 72 is positioned on the upper side of each of the second coupling members 71, 71 and faces to each other via the seat 16.

[0079] As illustrated in FIG. 18, in the folding vehicle 1 in the standing driving mode, when the component members of the wheelchair 101 (for example, the cross pipe 104 or the coupling pipe 105 as described above) are mounted on the recessed part 72 of the second coupling member 71, the wheelchair 101 is mounted in a state separating the rear wheels 102 from the running surface G. As a result, the wheelchair 101 can be moved by the

25

30

45

50

folding vehicle 1 in the standing driving mode.

[0080] A position where the wheelchair 101 having a foldable structure is mounted on the recessed part 72 of the second coupling member 71 and a position where the wheelchair 101 having a structure which is not able to be folded is mounted on the recessed part 72 of the second coupling member 71 are almost the same as the first coupling member 61 as described above (see FIG. 15).

[2.-3 Third coupling member]

[0081] Next, the third coupling member is described with reference to FIGs. 19 to 23. As illustrated in FIGs. 19 and 20, the third coupling members 81 are each attached to both end portions of the handle 4. The third coupling member 81 includes a main body 84 having the first coupling hole 82 and the second coupling hole 83. [0082] The first coupling hole 82 having the size into which the end portion of the handle 4 is fitted is formed in the main body 84. When the end portion of the handle 4 is inserted and fitted into the first coupling hole 82, the end portion of the handle 4 is fixed to the main body 84 by a fixing screw 85 screwed from an above of the main body 84. As a result, each of the third coupling members 81, 81 is fixed to the both end portions of the handle 4. [0083] The main body 84 is penetrated into the second coupling hole 83 having the size into which an end portion of the push-handle 103 of the wheelchair 101 (see FIGs. 14 and 18) can be inserted. When the end portion of the push-handle 103 is inserted into the second coupling hole 83, the end portion of the push-handle 103 is fixed to the main body 84 by a fixing screw 86 screwed from an outer side of the main body 84. As a result, the push-handle 103 is fixed to each of the third coupling members 81, 81. [0084] When the handle 4 and the push-handle 103 are coupled to each other via each of the third coupling members 81, 81 as described above, as illustrated in FIGs. 21 to 23, the folding vehicle 1 and the wheelchair 101 become continuous to each other.

[0085] As a result, the folding vehicle 1 can be moved while pushing the wheelchair 101. When the folding vehicle 1 is moved, the folding vehicle 1 is set in any one of the seated driving mode illustrated in FIG. 21, the folded mode illustrated in FIG. 22, and the standing driving mode illustrated in FIG. 23. In the folding vehicle 1, a driving state can be switched to any one of the seated driving mode illustrated in FIG. 21, the folded mode illustrated in FIG. 22, and the standing driving mode illustrated in FIG. 23 as described above while maintaining a state in which the folding vehicle 1 and the wheelchair 101 are continuous to each other.

[3. Summary]

[0086] As described above, the folding vehicle 1 according to the present embodiment can self-travel by the battery 14 and the in-wheel motor M in an independent

state in which the folding vehicle 1 is not coupled to the wheelchair 101. Further, the folding vehicle 1 can move the wheelchair 101 coupled thereto via any one of each of the coupling members 61, the coupling members 71, and the coupling members 81 by self-travelling of the battery 14 and the in-wheel motor M. Therefore, the folding vehicle 1 is capable of assisting power of the wheelchair 101 coupled to the folding vehicle 1 and is capable of traveling alone in a state of being detached from the wheelchair 101.

[0087] The folding vehicle 1 can move the wheelchair 101 coupled thereto via any one of each of the coupling members 61, the coupling members 71, and the coupling members 81 by self-travelling of the battery 14 and the in-wheel motor M. Therefore, the folding vehicle 1 reduces burdens on a caregiver of the wheelchair 101.

[0088] Further, the folding vehicle 1 can self-travel by the battery 14 and the in-wheel motor M in the independent state in which the folding vehicle 1 is not coupled to the wheelchair 101. Therefore, the folding vehicle 1 can contribute to cost reduction by being used as a self-travelling vehicle unrelated to the wheelchair 101.

[0089] In the folding vehicle 1, the rear wheels 102 of the wheelchair 101 are separated from the running surface G when the cross pipe 104 or the coupling pipe 105 of the wheelchair 101 is mounted on the recessed part 63 of the first coupling member 61. Therefore, since the rotation of the rear wheels 102 of the wheelchair 101 are unneeded at the time of moving the wheelchair 101 by self-travelling of the battery 14 and the in-wheel motor M, safety is ensured.

[0090] The recessed part 72 of the second coupling member 71 is the same as the above in this regard.

[0091] In the folding vehicle 1, when the driving state is set in the standing driving mode, the second coupling member 71 becomes closer to the running surface G, the second coupling member 71 is erected between the pair of rear wheels 20, 20 and the recessed part 72 is positioned on the upper side of the second coupling member 71. Therefore, the cross pipe 104 or the coupling pipe 105 of the wheelchair 101 becomes easy to mount on the recessed part 72 of the second coupling member 71 and the burdens on the caregiver of the wheelchair 101 are further reduced.

[0092] The recessed part 63 of the first coupling member 61 is the same as the above in this regard.

[0093] In the folding vehicle 1, when the push-handle 103 of the wheelchair 101 is fixed to the handle 4 by the third coupling member 81, a moving operation of the wheelchair 101 is performed by an operation of the handle 4 for self-traveling of the battery 14 and the in-wheel motor M. At that time, the folding vehicle 1 can move the wheelchair 101 in any one of the seated driving mode illustrated in FIG. 21, the folded mode illustrated in FIG. 23. [0094] Since the size of the folding vehicle 1 is small in the folded mode illustrated in FIG. 22, it becomes easy to move the wheelchair 101 by the folding vehicle 1 in a

narrow space such as the interior of a room. Further, since the seat 16 and the handle 4 are close to each other and the caregiver who is a driver of the folding vehicle 1 and a passenger of the wheelchair 101 are positioned closer to each other in the folded mode illustrated in FIG. 22, communication becomes easier between them, and their affinity is improved.

[0095] In the present embodiment, the folding vehicle 1 is an example of the "small-sized electric vehicle". The main frame mechanism 9 is an example of the "main frame". The battery 14 and the in-wheel motor M are an example of the "electric mechanism". The seated driving mode is an example of the "first seated driving mode". The folded mode is an example of the "second seated driving mode". The first coupling member 61 is an example of the "coupling member", the "mounting member", and the "receiving member". The second coupling member 71 is an example of the "coupling member", the "mounting member" and the "receiving member". The third coupling member 81 is an example of the "coupling member", the "mounting member", and the "joining member". The cross pipe 104 of the wheelchair 101 is an example of the "component member of the wheelchair". The coupling pipe 105 of the wheelchair 101 is an example of the "component member of the wheelchair".

[4. Modification]

[0096] The present invention is not limited to embodiments as described above, and the various changes, substitutions, and alterations could be made hereto without departing from the scope of the invention.

[0097] For example, in the present embodiment, the first coupling member 61 or the second coupling member 71 may be provided in a self-travelling type small-sized electric vehicle that is set only in the standing driving mode.

[0098] The third coupling member 81 may be provided in a self-traveling type small-sized electric vehicle that is set in any one of the folded mode, the seated driving mode, and the standing driving mode.

[0099] In the present embodiment, a mounting member may be provided in the folding vehicle 1 instead of the first coupling member 61, the second coupling member 71, and the third coupling member 81. The abovementioned mounting member is for coupling the wheelchair 101 to the folding vehicle 1, and for example, a boss (protrusion), a pin, a belt, a hook, or a clamp etc.

[0100] In the present embodiment, when a brake lever provided in the handle 4 is moved, the folding vehicle 1 may comprise an interlocking mechanism for moving a brake lever for care provided in the push-handle 103 of the wheelchair 101. In such a case, a braking operation in the brake lever for care of the wheelchair 101 is performed by a braking operation in the brake lever of the handle 4.

[0101] In the present embodiment, a drive source of the folding vehicle 1 is not limited to the in-wheel motor

M. The other motors may be accepted as long as the motor is a motor driven by the battery 14.

EXPLANATION OF REFERENCE NUMERALS

[0102]

- 1 folding vehicle
- 2 base frame
- 3 front frame
 - 4 handle
 - 9 main frame mechanism
 - 13 board
 - 14 battery
- 16 seat (seat part)
 - 18 swing arm
 - 20 a pair of rear wheel
 - 61 first coupling member
- 63 recessed part of the first coupling member
- 71 second coupling member
 - 72 recessed part of the second coupling member
 - 81 third coupling member
 - 101 wheelchair
 - 102 rear wheels of the wheelchair
 - 103 push-handle of the wheelchair
 - 104 cross pipe of the wheelchair
 - 105 coupling pipe of the wheelchair
 - M in-wheel motor
 - G running surface

Claims

30

35

40

- 1. A small-sized electric vehicle (1) comprising:
 - a main frame (9);
 - a board (13) that is attached to the main frame
 - a swing arm (18), the swing arm (18) including:
 - one end pivotally that is supported by the main frame (9); and
 - another end at which a pair of rear wheels (20) is pivotally supported;
 - an electric mechanism (14, M) that is capable of making the small-sized electric vehicle (1) alone self-travel;
 - a coupling member (61, 71) that is configured to couple a wheelchair (101) to the small-sized electric vehicle (1);
 - a mounting member (61, 71) that is configured to mount the wheelchair (101) on the small-sized electric vehicle (1), as the coupling member (61, 71); and
 - a receiving member (61,71) that is provided with a recessed part (63,72) on which a component member (104, 105) of the wheelchair (101) is

25

30

35

40

50

55

mounted, as the mounting member (61, 71), characterized by

a seat (16) that is mounted on an upper end portion of the main frame (9), wherein

the small-sized electric vehicle (1) is switchable between a first seated driving mode, in which driving while being seated on the seat (16) is enabled and a standing driving mode, in which driving while standing on the board (13) positioned nearly parallel to the running surface (G) along with the seat (16) is enabled, achieved by pivoting the main frame (9) toward the swing arm (18) in the first seated driving mode,

when the first seated driving mode is switched to the standing driving mode, the receiving member (61, 71) is erected between the pair of rear wheels (20) and the recessed part (63, 72) is positioned on an upper side of the receiving member (61, 71), and

when the component member (104, 105) of the wheelchair (101) is mounted on the recessed part (63, 73) of the receiving member (61, 71), rear wheels (102) of the wheelchair (101) are separated from a running surface (G).

- The small-sized electric vehicle (1) according to claim 1, wherein the receiving member (61) is provided in the swing arm (18).
- The small-sized electric vehicle (1) according to claim 1, wherein the receiving member (71) is provided in the seat (16).
- 4. A small-sized electric vehicle (1) comprising:

a main frame (9);

a board (13) that is attached to the main frame (9);

a swing arm (18), the swing arm (18) including:

one end that is pivotally supported by the main frame (9); and

another end at which a pair of rear wheels (20) is pivotally supported;

an electric mechanism (14, M) that is capable of making the small-sized electric vehicle (1) alone self-travel; and

a coupling member (81) that is configured to couple a wheelchair (101) to the small-sized electric vehicle (1); **characterized by**

a seat (16) that is mounted on an upper end portion of the main frame (9);

a handle (4) that operates self-traveling of the small-sized electric vehicle (1) by the electric mechanism (14, M); and

a joining member (81) that is configured to fix a push-handle (103) of the wheelchair (101) to the handle (4), as the coupling member (81), wherein

the small-sized electric vehicle (1) is switchable between a first seated driving mode, in which driving while being seated on the seat (16) is enabled and a standing driving mode, in which driving while standing on the board (13) positioned nearly parallel to a running surface (G) along with the seat (16) is enabled, achieved by pivoting the main frame (9) toward the swing arm (18) in the first seated driving mode.

5 5. The small sized electric vehicle (1) according to claim4 comprising:

a brake lever that is provided in the handle; and an interlocking mechanism that moves a brake lever for care provided in the push-handle (103) of the wheelchair (101) when the brake lever is moved.

6. The small-sized electric vehicle (1) according to claim 4 or claim 5 comprising:

a front frame (3) that is included an upper end to which the handle (4) is attached;

a base frame (2) at which the front frame (3) is pivotally supported;

a main frame (9) that is pivotally supported with respect to the base frame (2); and

a seat (16) that is mounted on an upper end portion of the main frame (9), wherein

the small-sized electric vehicle (1) is switchable between a first seated driving mode, in which driving while being seated on the seat (16) is enabled and a second seated driving mode, in which the seat (16) and the handle (4) are close to each other, achieved by pivoting the main frame (9) toward the front frame (3) in the first seated driving mode.

¹⁵ Patentansprüche

1. Elektrokleinfahrzeug (1) mit:

einem Hauptrahmen (9);

einer Platte (13), die an dem Hauptrahmen (9) befestigt ist;

einem Schwenkarm (18), wobei der Schwenkarm (18) Folgendes aufweist:

ein schwenkbares Ende, das durch den Hauptrahmen (9) abgestützt ist; und ein anderes Ende, an welchem ein Paar Hinterräder (20) schwenkbar abgestützt ist;

15

20

25

35

45

50

55

einem elektrischen Mechanismus (14, M), der in der Lage ist, das Elektrokleinfahrzeug (1) zum alleinigen Selbstfahren zu bringen;

einem Kopplungselement (61, 71), das konfiguriert ist, einen Rollstuhl (101) an das Elektrokleinfahrzeug (1) zu koppeln;

einem Montageelement (61, 71), das konfiguriert ist, als das Kopplungselement (61, 71) den Rollstuhl (101) an dem Elektrokleinfahrzeug (1) zu montieren; und

einem Aufnahmeelement (61, 71), das als das Montageelement (61, 71) mit einem vertieften Teil (63, 72) versehen ist, an welchem ein Bauteilelement (104, 105) des Rollstuhls (101) montiert ist, **gekennzeichnet durch**

einen Sitz (16), der an einem oberen Endabschnitt des Hauptrahmens (9) montiert ist, wobei

das Elektrokleinfahrzeug (1) zwischen einem ersten Sitzantriebsmodus, in welchem ein Antreiben ermöglicht ist, während auf dem Sitz (16) gesessen wird, und einem Stehantriebsmodus umschaltbar ist, in welchem ein Antreiben ermöglicht ist, während auf der Platte (13) gestanden wird, die zusammen mit dem Sitz (16) nahezu parallel zu der Lauffläche (G) positioniert ist, was erreicht wird, indem der Hauptrahmen (9) in dem ersten Sitzantriebsmodus in Richtung des Schwenkarms (18) geschwenkt wird,

beim Umschalten des ersten Sitzantriebsmodus zu dem Stehantriebsmodus das Aufnahmeelement (61, 71) zwischen dem Paar Hinterräder (20) aufgerichtet wird und der vertiefte Teil (63, 72) auf einer Oberseite des Aufnahmeelements (61, 71) positioniert wird und

beim Montieren des Bauteilelements (104, 105) des Rollstuhls (101) an dem vertieften Teil (63, 73) des Aufnahmeelements (61, 71) Hinterräder (102) des Rollstuhls (101) von einer Lauffläche (G) getrennt werden.

- Elektrokleinfahrzeug (1) nach Anspruch 1, wobei das Aufnahmeelement (61) bei dem Schwenkarm (18) vorgesehen ist.
- 3. Elektrokleinfahrzeug (1) nach Anspruch 1, wobei das Aufnahmeelement (71) bei dem Sitz (16) vorgesehen ist.
- 4. Elektrokleinfahrzeug (1) mit:

einem Hauptrahmen (9); einer Platte (13), die an dem Hauptra

einer Platte (13), die an dem Hauptrahmen (9) befestigt ist;

einem Schwenkarm (18), wobei der Schwenkarm (18) Folgendes aufweist:

ein Ende, das durch den Hauptrahmen (9) schwenkbar abgestützt ist; und

ein anderes Ende, an welchem ein Paar Hinterräder (20) schwenkbar abgestützt ist;

einem elektrischen Mechanismus (14, M), der in der Lage ist, das Elektrokleinfahrzeug (1) zum alleinigen Selbstfahren zu bringen; und

einem Kopplungselement (81), das konfiguriert ist, einen Rollstuhl (101) an das Elektrokleinfahrzeug (1) zu koppeln; **gekennzeichnet durch** einen Sitz (16), der an einem oberen Endabschnitt des Hauptrahmens (9) montiert ist; einen Griff (4), der ein Selbstfahren des Elektrokleinfahrzeugs (1) durch den elektrischen Mechanismus (14, M) bedient; und

ein Verbindungselement (81), das konfiguriert ist, als das Kopplungselement (81) einen Schiebegriff (103) des Rollstuhls (101) an dem Griff (4) zu fixieren, wobei

das Elektrokleinfahrzeug (1) zwischen einem ersten Sitzantriebsmodus, in welchem ein Antreiben ermöglicht ist, während auf dem Sitz (16) gesessen wird, und einem Stehantriebsmodus umschaltbar ist, in welchem ein Antreiben ermöglicht ist, während auf der Platte (13) gestanden wird, die zusammen mit dem Sitz (16) nahezu parallel zu einer Lauffläche (G) positioniert ist, was erreicht wird, indem der Hauptrahmen (9) in dem ersten Sitzantriebsmodus in Richtung des Schwenkarms (18) geschwenkt wird.

5. Elektrokleinfahrzeug (1) nach Anspruch 4, mit:

einem Bremshebel, der bei dem Griff vorgesehen ist; und

einem Verriegelungsmechanismus, der beim Bewegen des Bremshebels einen Bremshebel für die Pflege bewegt, der bei dem Schiebegriff (103) des Rollstuhls (101) vorgesehen ist.

6. Elektrokleinfahrzeug (1) nach Anspruch 4 oder Anspruch 5, mit:

einem vorderen Rahmen (3), der ein oberes Ende aufweist, an welchem der Griff (4) befestigt ist:

einem Basisrahmen (2), an welchem der vordere Rahmen (3) schwenkbar abgestützt ist; einem Hauptrahmen (9), der bezüglich des Basisrahmens (2) schwenkbar abgestützt ist; und einem Sitz (16), der an einem oberen Endabschnitt des Hauptrahmens (9) montiert ist, wobei

das Elektrokleinfahrzeug (1) zwischen einem ersten Sitzantriebsmodus, in welchem ein Antreiben ermöglicht ist, während auf dem Sitz (16) gesessen wird, und einem zweiten Sitzantriebsmodus umschaltbar ist, in welchem der Sitz (16) und der Griff (4) nahe beieinander sind, was erreicht wird, indem der Hauptrahmen (9) in dem

15

20

25

ersten Sitzantriebsmodus in Richtung des vorderen Rahmens (3) geschwenkt wird.

Revendications

1. Véhicule électrique de petite taille (1), comprenant :

un cadre principal (9);

un panneau (13) qui est attaché au cadre principal (9) ;

un bras oscillant (18), le bras oscillant (18) incluant :

une extrémité qui est supportée de façon pivotante par le cadre principal (9) ; et une autre extrémité à laquelle une paire de roues arrière (20) est supportée de façon pivotante ;

un mécanisme électrique (14, M) qui est capable de faire en sorte que le véhicule électrique de petite taille (1) se déplace seul de façon autonome;

un élément d'accouplement (61, 71) qui est configuré pour accoupler un fauteuil roulant (101) au véhicule électrique de petite taille (1);

un élément de montage (61,71) qui est configuré pour monter le fauteuil roulant (101) sur le véhicule électrique de petite taille (1), comme l'élément d'accouplement (61,71) ; et

un élément de réception (61, 71) qui est pourvu d'une partie évidée (63, 72) sur laquelle un élément composant (104, 105) du fauteuil roulant (101) est monté, comme l'élément de montage (61, 71), caractérisé par

un siège (16) qui est monté sur une portion d'extrémité supérieure du cadre principal (9), dans lequel

le véhicule électrique de petite taille (1) est permutable entre un premier mode de conduite assis, dans lequel la conduite tout en étant assis sur le siège (16) est possible, et un mode de conduite debout, dans lequel la conduite tout en étant debout sur le panneau (13) positionné presque parallèlement à la surface de roulement (G), conjointement avec le siège (16), est possible, accompli en faisant pivoter le cadre principal (9) vers le bras oscillant (18) dans le premier mode de conduite assis,

lorsque le premier mode de conduite assis est permuté au mode de conduite debout, l'élément de réception (61, 71) est levé entre la paire de roues arrière (20) et la partie évidée (63, 72) est positionnée sur un côté supérieur de l'élément de réception (61, 71), et

lorsque l'élément composant (104, 105) du fauteuil roulant (101) est monté sur la partie évidée (63, 73) de l'élément de réception (61, 71), les roues arrière (102) du fauteuil roulant (101) sont séparées d'une surface de roulement (G).

- Véhicule électrique de petite taille (1) selon la revendication 1, dans lequel l'élément de réception (61) est prévu dans le bras oscillant (18).
 - 3. Véhicule électrique de petite taille (1) selon la revendication 1, dans lequel l'élément de réception (71) est prévu dans le siège (16).
 - 4. Véhicule électrique de petite taille (1), comprenant :

un cadre principal (9);

un panneau (13) qui est attaché au cadre principal (9);

un bras oscillant (18), le bras oscillant (18) incluant :

une extrémité qui est supportée de façon pivotante par le cadre principal (9) ; et une autre extrémité à laquelle une paire de roues arrière (20) est supportée de façon pivotante ;

un mécanisme électrique (14, M) qui est capable de faire en sorte que le véhicule électrique de petite taille (1) se déplace seul de façon autonome ; et

un élément d'accouplement (81) qui est configuré pour accoupler un fauteuil roulant (101) au véhicule électrique de petite taille

(1) ; caractérisé par

un siège (16) qui est monté sur une portion d'extrémité supérieure du cadre principal (9);

une poignée (4) qui active le déplacement autonome du véhicule électrique de petite taille (1) par le mécanisme électrique (14, M); et

un élément de jonction (81) qui est configuré pour fixer une poignée à pousser (103) du fauteuil roulant (101) à la poignée (4), comme l'élément d'accouplement (81), dans lequel

le véhicule électrique de petite taille (1) est permutable entre un premier mode de conduite assis, dans lequel la conduite tout en étant assis sur le siège (16) est possible, et un mode de conduite debout, dans lequel la conduite tout en étant debout sur le panneau (13) positionné presque parallèlement à une surface de roulement (G) conjointe-

12

incluant :

40

45

35

ment avec le siège (16) est possible, accompli en faisant pivoter le cadre principal (9) vers le bras oscillant (18) dans le premier mode de conduite assis.

5. Véhicule électrique de petite taille (1) selon la revendication 4, comprenant :

un levier de frein qui est prévu dans la poignée ; et

un mécanisme d'enclenchement qui meut un levier de frein, pour des soins, prévu dans la poignée à pousser (103) du fauteuil roulant (101) lorsque le levier de frein est mû.

6. Véhicule électrique de petite taille (1) selon la revendication 4 ou la revendication 5, comprenant :

un cadre avant (3) qui est inclus à une extrémité supérieure à laquelle la poignée (4) est attachée;

un cadre de base (2) sur lequel le cadre avant (3) est supporté de façon pivotante ;

un cadre principal (9) qui est supporté de façon pivotante par rapport au cadre de base (2) ; et un siège (16) qui est monté sur une portion d'extrémité supérieure du cadre principal (9), dans lequel

le véhicule électrique de petite taille (1) est permutable entre un premier mode de conduite assis, dans lequel la conduite tout en étant assis sur le siège (16) est possible, et un second mode de conduite assis, dans lequel le siège (16) et la poignée (4) sont près l'un de l'autre, accompli en faisant pivoter le cadre principal (9) vers le cadre avant (3) dans le premier mode de conduite assis.

10

5

15

20

25

30

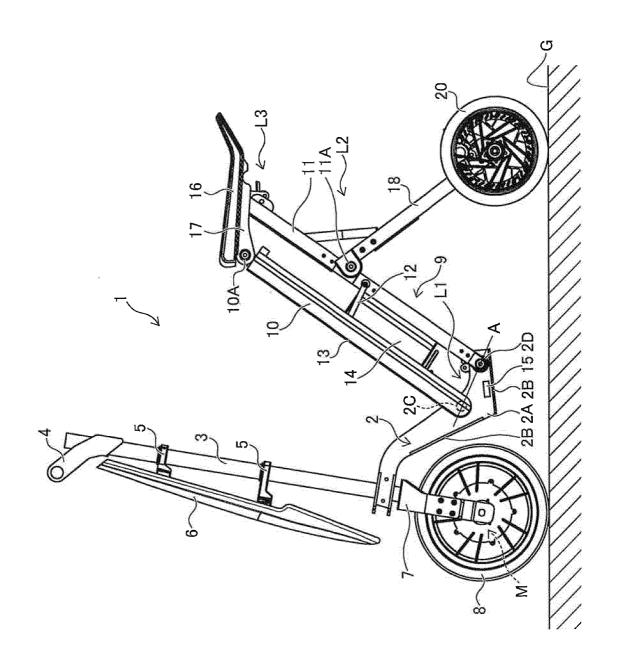
35

40

45

50





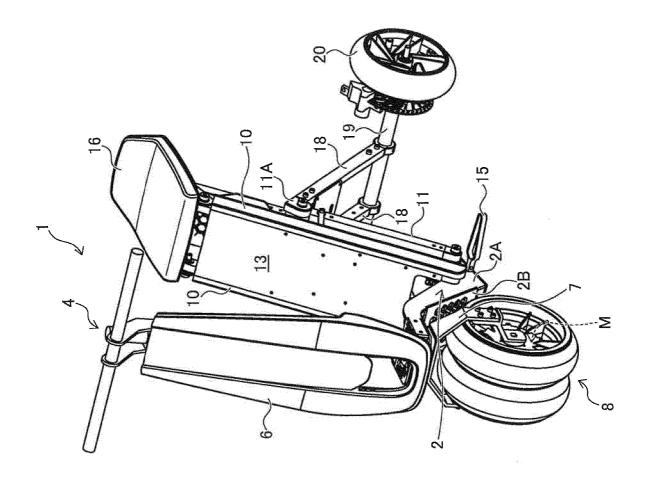


FIG. 3

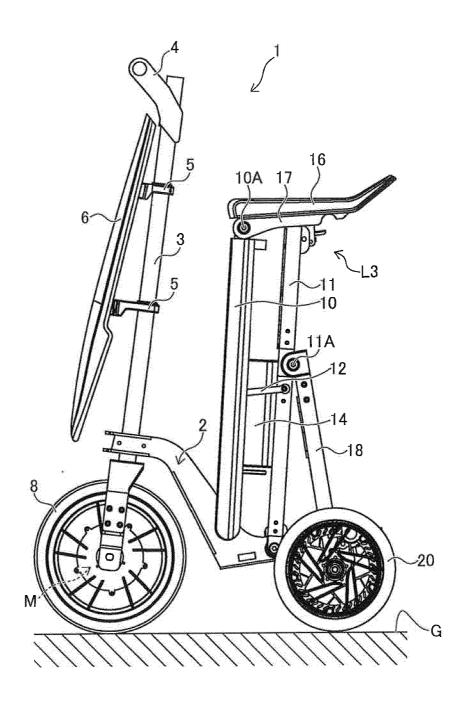
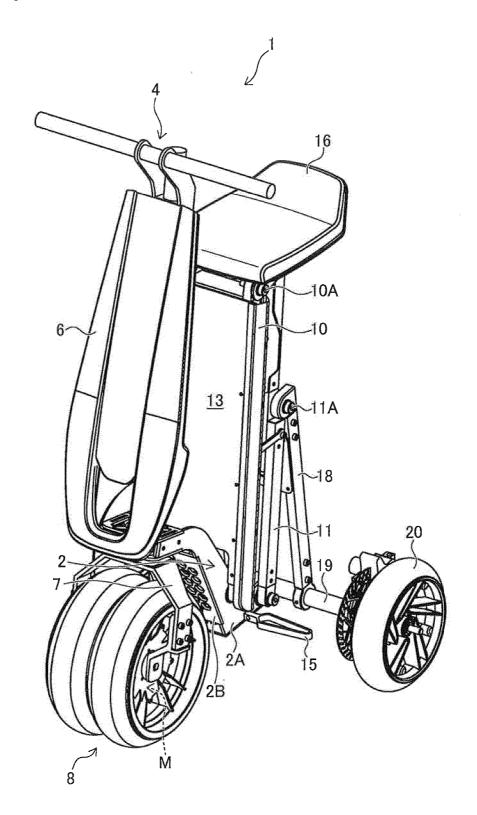
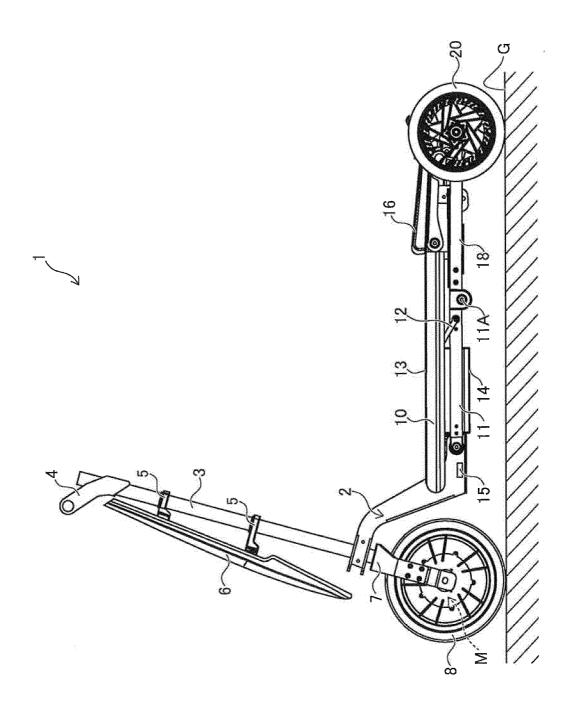
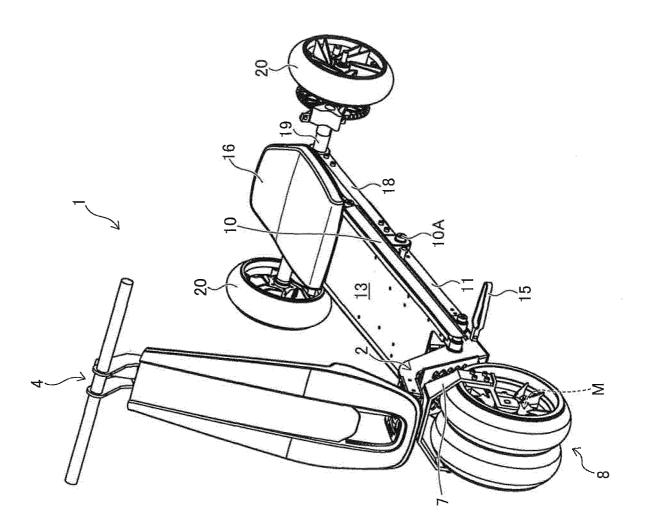


FIG. 4





で (の (の



(O)

FIG. 7(a)

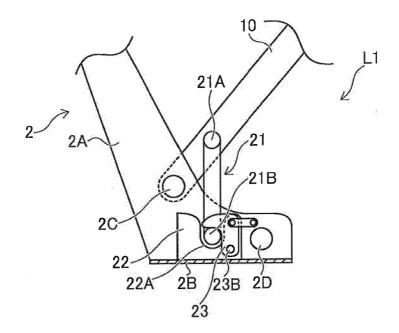


FIG. 7(b)

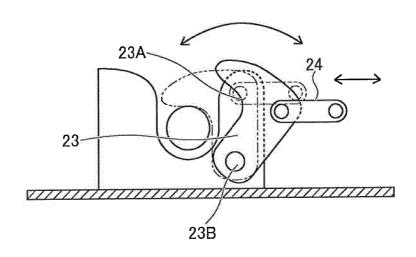


FIG. 8

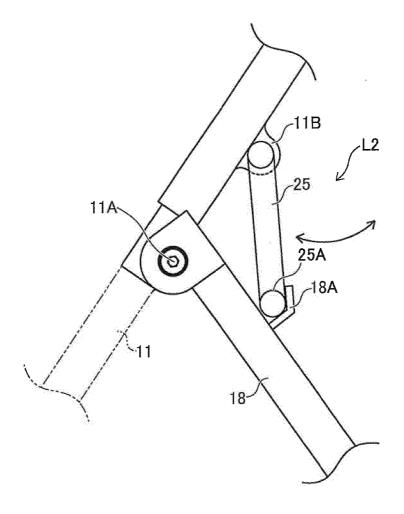


FIG. 9(a)

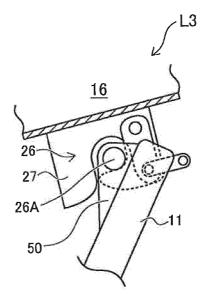
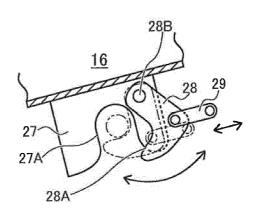
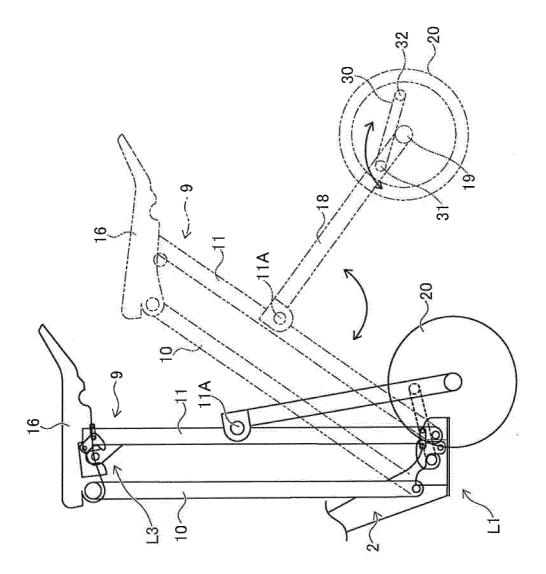


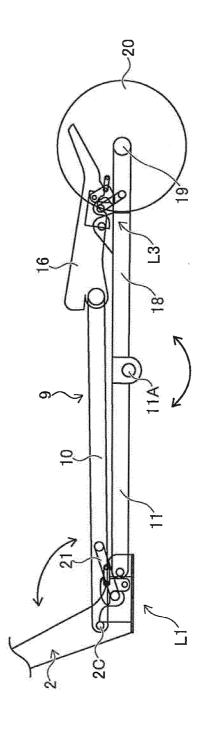
FIG. 9(b)



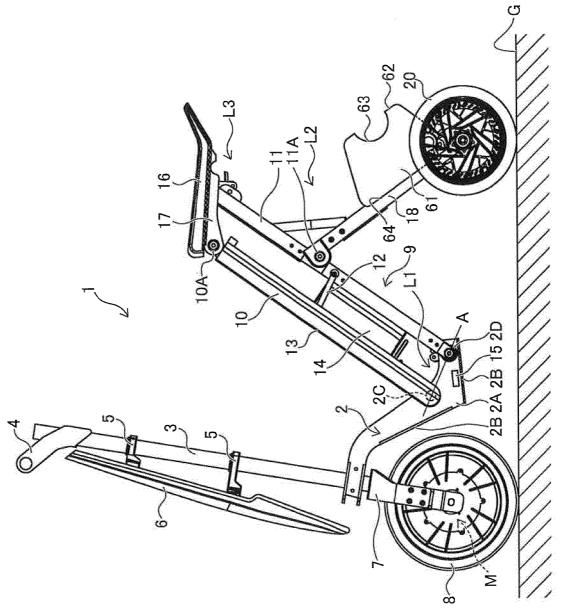


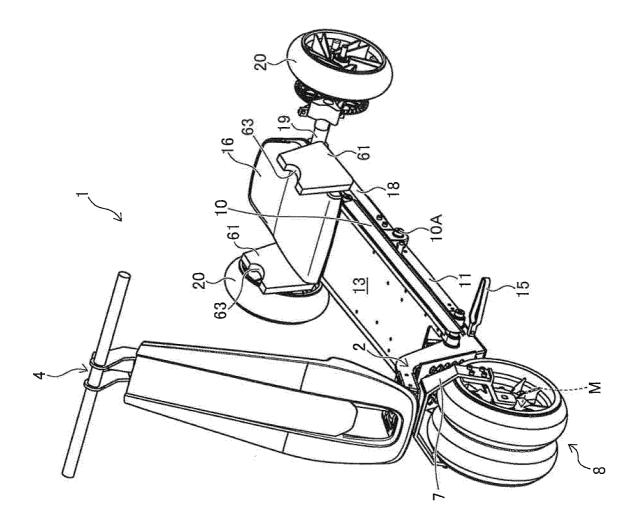
FG. 40

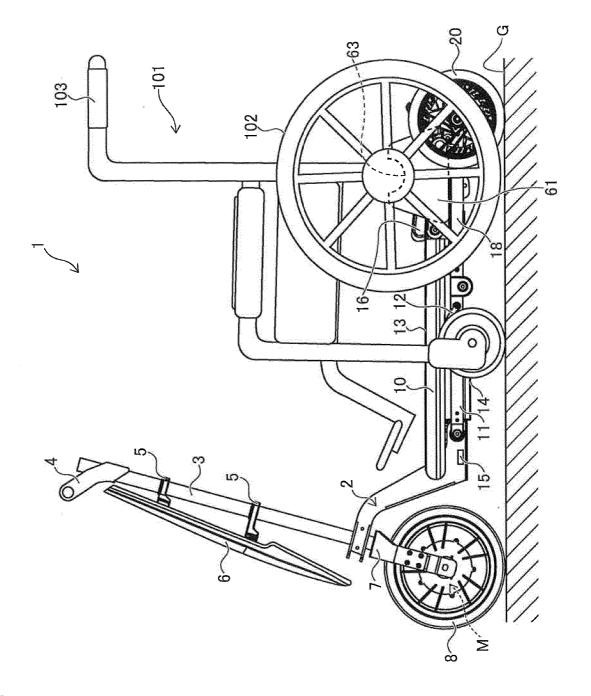
(C)

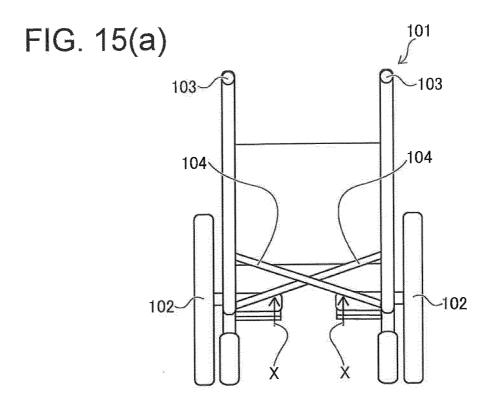


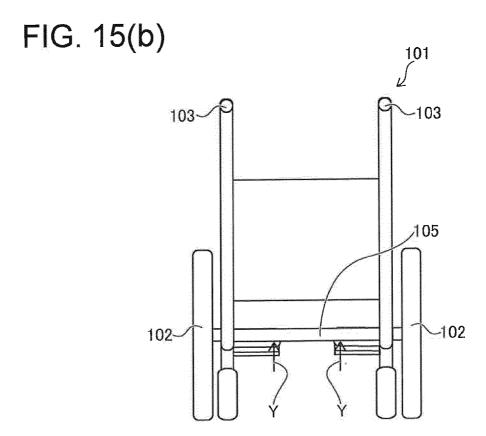


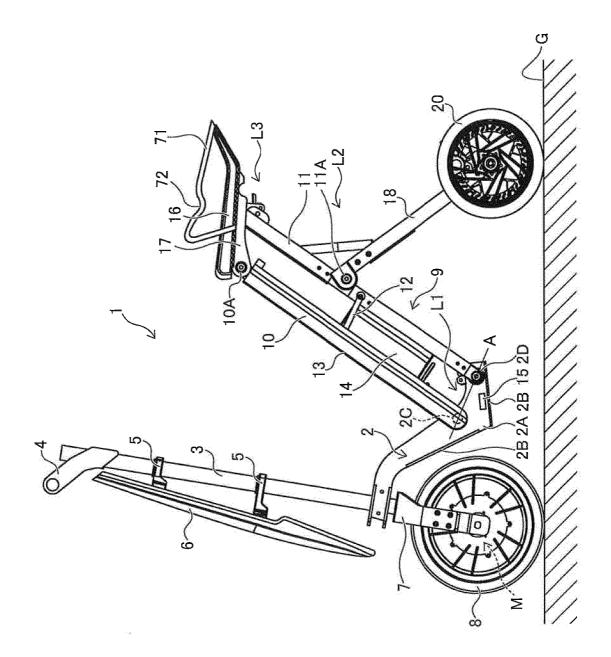


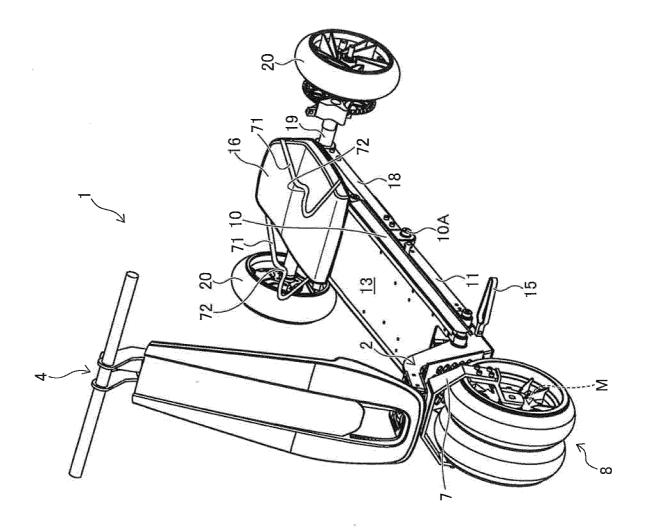


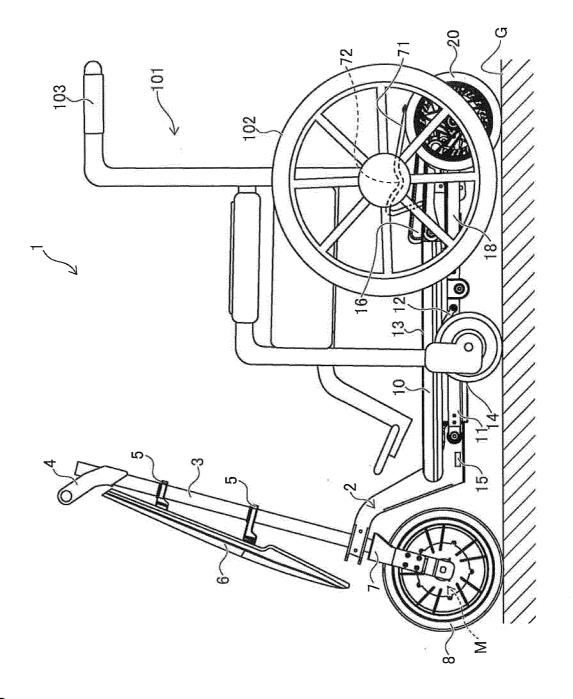


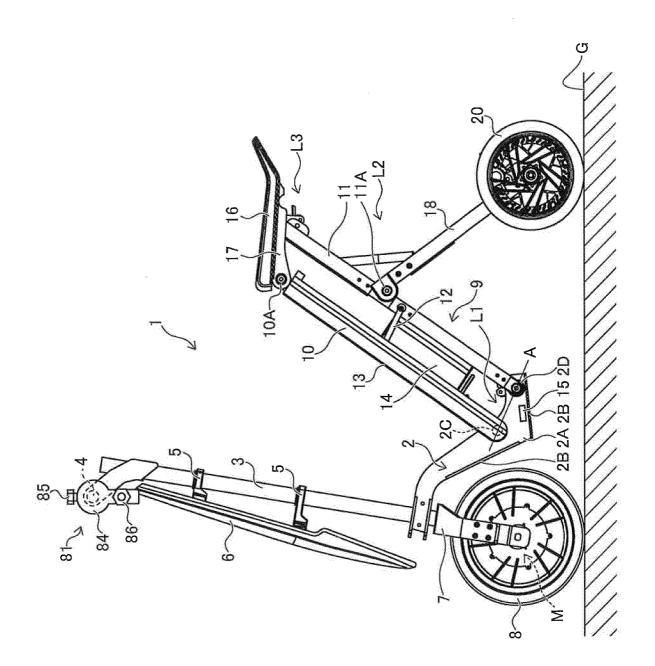












而 (2)

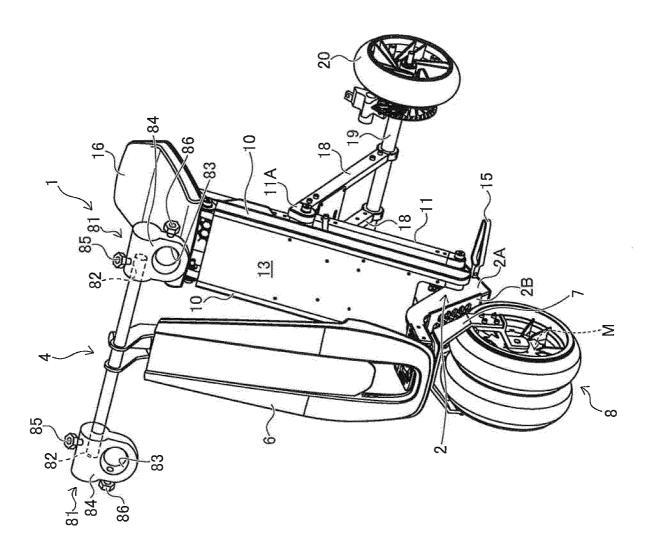
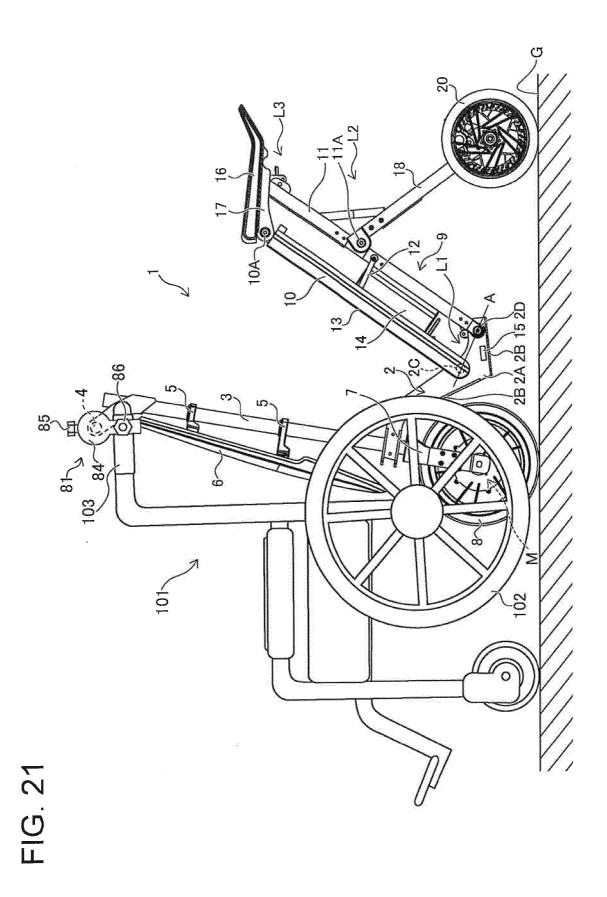
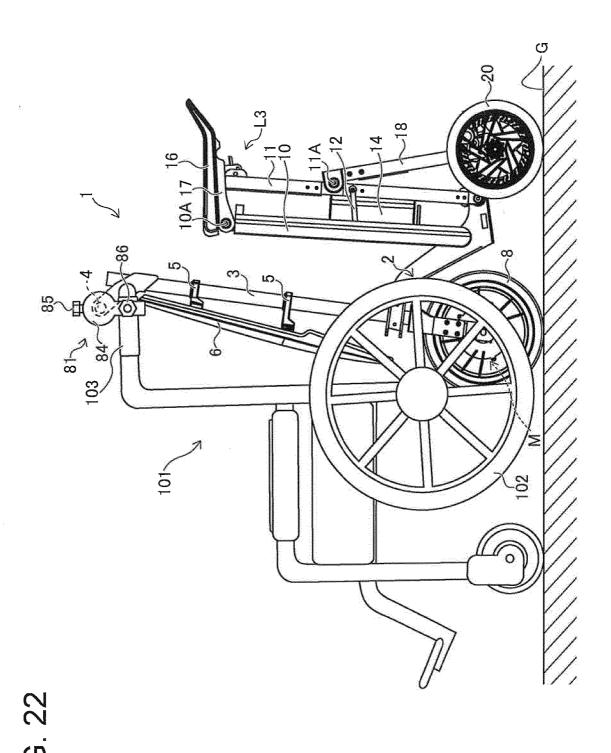
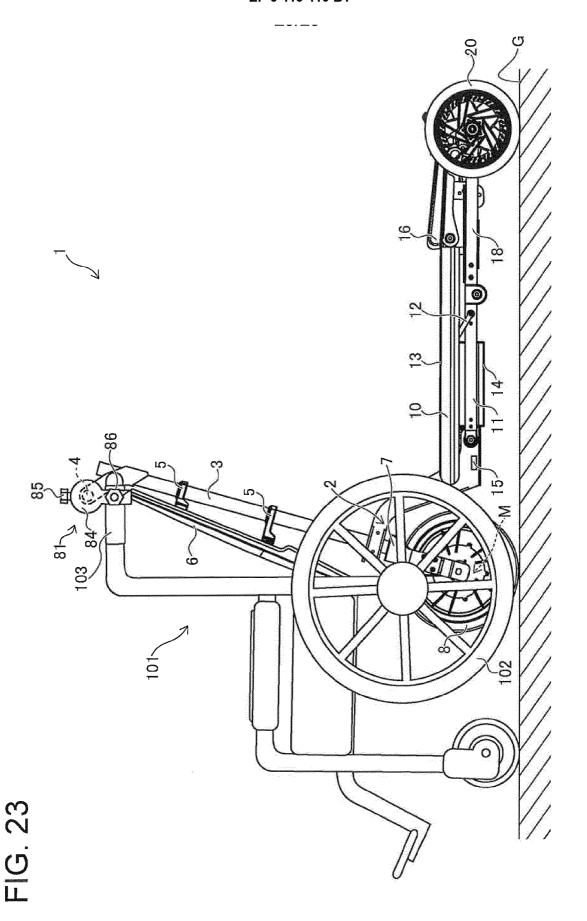


FIG. 20







EP 3 415 410 B1

REFERENCES CITED IN THE DESCRIPTION

This list of references cited by the applicant is for the reader's convenience only. It does not form part of the European patent document. Even though great care has been taken in compiling the references, errors or omissions cannot be excluded and the EPO disclaims all liability in this regard.

Patent documents cited in the description

- JP 2006000589 A **[0002]**
- US 5351774 A [0003]
- JP 2011087728 A **[0003]**
- US 20120029697 A1 [0003]
- CA 2487630 A1 [0003]

- JP 2015128921 A **[0003]**
- US 2015068828 A1 [0003]
- US 2007051548 A1 [0003]
- JP 2012056363 A **[0003]**